

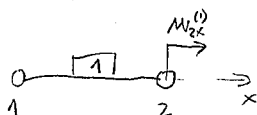
1D ELASTICITY

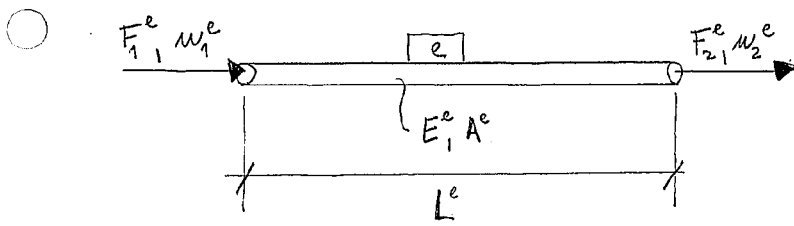
- FEM seeks for the minimum potential energy of the system
- equilibrium found using variational principles
- FEM steps:
 - 1) subdividing the problem domain (= discretization, e.g. subdivision of truss to members connected at nodes) \Rightarrow into "finite elements"
 - 2) element formulation: development of equations for elements (e.g. stiffness of each element - i.e. its response to loading)
 - 3) assembly: obtaining the equations of the entire system from the equations of individual elements (creating "global matrix")
 - 4) solving the equations
 - 5) postprocessing: determining quantities of interest (e.g. stresses) + visualization

BAR ELEMENT (direct stiffness method)

- slender \rightarrow no resistance to torsion, bending and shear
 - \rightarrow only axial internal forces
- equivalent to spring

- notation: $w_{2x}^{(1)} = w_2^{(1)} = x$ -component of displacement at node 2 of element 1





internal force: F^e
 stress: $\sigma^e = \frac{F^e}{A^e}$ (tension = positive)

bar behavior: a) equilibrium (sum of nodal forces is zero):
 $F_1^e + F_2^e = 0$

b) Hooke's law: $\sigma^e = E^e \epsilon^e$

c) structure is continuous (no gaps or overlaps):
 $\epsilon^e = \frac{w_2^e - w_1^e}{L^e}$

nodal forces:

$$F_1^e = -F_e \text{ (internal force)} = -A^e \sigma^e = -A^e E^e \epsilon^e = -\frac{E^e A^e}{L^e} (w_2^e - w_1^e) = \frac{E^e A^e}{L^e} (w_1^e - w_2^e)$$

$$F_2^e = \frac{E^e A^e}{L^e} (w_2^e - w_1^e)$$

in matrix form:
$$\begin{bmatrix} F_1^e \\ F_2^e \end{bmatrix} = \frac{E^e A^e}{L^e} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} w_1^e \\ w_2^e \end{bmatrix}$$

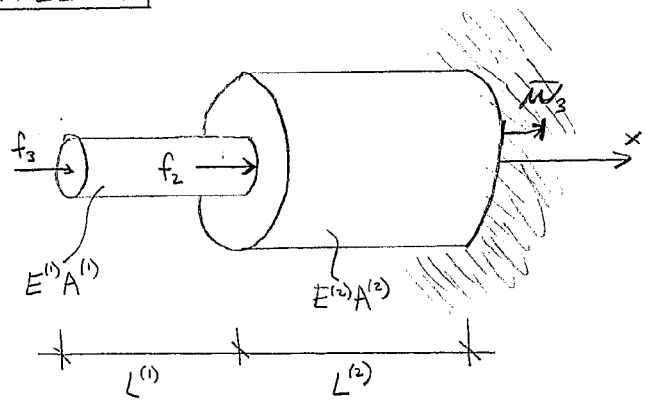
$\underline{F}^e = \underline{K}^e \underline{w}^e$

↓
symmetric
($\underline{K}^e = (\underline{K}^e)^T$)

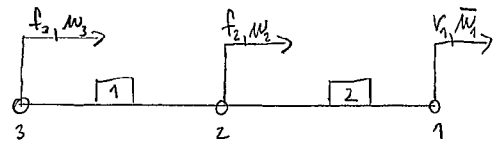
- the equation $\underline{F}^e = \underline{K}^e \underline{w}^e$ describes the behavior of an element

- because of linearity in Hooke's law and strain-displacement relationship the system is linear

EXAMPLE 1

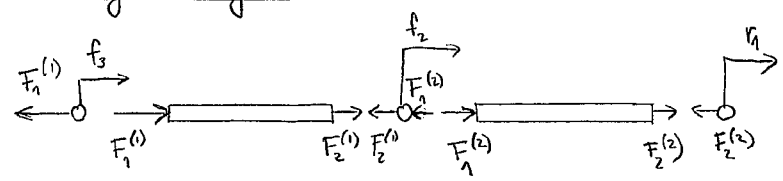


scheme :



- 1) discretization : nodes where load is applied and properties of the structure change
- 2) at nodes with prescribed displacement \bar{u} the force is referred to as a reaction (it is unknown)
- 3) at nodes with known force the displacement must be unknown
- 4) for each bar element the nodal forces are related to nodal displacements via stiffness matrix $\underline{F}^e = \underline{k}^e \underline{d}^e$

free body diagram :



- global system of equations from compatibility between elements and nodal equilibrium
- the forces exerted by the elements on the nodes are equal and opposite

contributions of
element 1:

element 2:

unknown forces
(=reactions)

$$\begin{matrix} \text{node 1} \\ \text{node 2} \\ \text{node 3} \end{matrix} \begin{bmatrix} 0 \\ F_2^{(1)} \\ F_1^{(1)} \end{bmatrix} + \begin{bmatrix} F_2^{(2)} \\ F_1^{(2)} \\ 0 \end{bmatrix} = \underbrace{\begin{bmatrix} 0 \\ f_2 \\ f_3 \end{bmatrix}}_{\underline{f} \text{ - prescribed at nodes}} + \begin{bmatrix} r_1 \\ 0 \\ 0 \end{bmatrix}$$

- element stiffness equation for element 1: $\begin{bmatrix} F_1^{(1)} \\ F_2^{(1)} \end{bmatrix} = \begin{bmatrix} k^{(1)} & -k^{(1)} \\ -k^{(1)} & k^{(1)} \end{bmatrix} \begin{bmatrix} w_3 \\ w_2 \end{bmatrix}$

$$\begin{matrix} \text{①} \\ \text{②} \\ \text{③} \end{matrix} \underbrace{\begin{bmatrix} 0 & 0 & 0 \\ 0 & k^{(1)} & -k^{(1)} \\ 0 & -k^{(1)} & k^{(1)} \end{bmatrix}}_{\underline{K}^{(1)}} \underbrace{\begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix}}_{\underline{d}} + \begin{matrix} \text{①} \\ \text{②} \\ \text{③} \end{matrix} \underbrace{\begin{bmatrix} k^{(2)} & -k^{(2)} & 0 \\ -k^{(2)} & k^{(2)} & 0 \\ 0 & 0 & 0 \end{bmatrix}}_{\underline{K}^{(2)}} \underbrace{\begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix}}_{\underline{d}} = \underbrace{\begin{bmatrix} 0 \\ f_2 \\ f_3 \end{bmatrix}}_{\underline{f}} + \underbrace{\begin{bmatrix} r_1 \\ 0 \\ 0 \end{bmatrix}}_{\underline{r}}$$

$$(\underline{K}^{(1)} + \underline{K}^{(2)}) \underline{d} = \underline{f} + \underline{r}$$

global stiffness matrix

$$\underline{K} = \sum_{e=1}^{n_{el}} \underline{K}^e = \begin{bmatrix} k^{(2)} & -k^{(2)} & 0 \\ -k^{(2)} & k^{(1)}+k^{(2)} & -k^{(1)} \\ 0 & -k^{(1)} & k^{(1)} \end{bmatrix} \begin{matrix} \text{①} \\ \text{②} \\ \text{③} \end{matrix}$$

singular matrix \rightarrow
we need boundary
conditions

- essential boundary conditions on "E-nodes" \rightarrow prescribed displ.
- forces prescribed at free "F-nodes"

$$\underline{d} = \begin{bmatrix} \underline{d}_E \\ \underline{d}_F \end{bmatrix} \quad \underline{f} = \begin{bmatrix} \underline{f}_E \\ \underline{f}_F \end{bmatrix} \quad \underline{r} = \begin{bmatrix} \underline{r}_E \\ \underline{r}_F \end{bmatrix}$$

\emptyset no reactions at free nodes

$$\begin{bmatrix} k^{(2)} & -k^{(2)} & 0 \\ -k^{(2)} & k^{(1)}+k^{(2)} & -k^{(1)} \\ 0 & -k^{(1)} & k^{(1)} \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix} = \begin{bmatrix} r_1 \\ -4 \\ 10 \end{bmatrix} \rightarrow \begin{bmatrix} \underline{K}_E & \underline{K}_{EF} \\ \underline{K}_{EF}^T & \underline{K}_F \end{bmatrix} \begin{bmatrix} \underline{d}_E \\ \underline{d}_F \end{bmatrix} = \begin{bmatrix} \underline{r}_E \\ \underline{f}_F \end{bmatrix}$$

$$\Rightarrow \underline{k}_{EF}^T \underline{d}_E + \underline{k}_F \underline{d}_F = \underline{f}_F \Rightarrow$$

$$\text{displacements: } \underline{d}_F = \underline{k}_F^{-1} (\underline{f}_F - \underline{k}_{EF}^T \underline{d}_E)$$

$$\text{reactions: } \underline{r}_E = \underline{k}_E \underline{d}_E + \underline{k}_{EF} \underline{d}_F$$

Penalty method

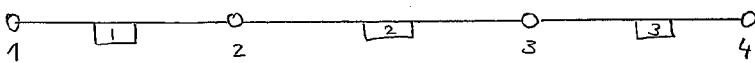
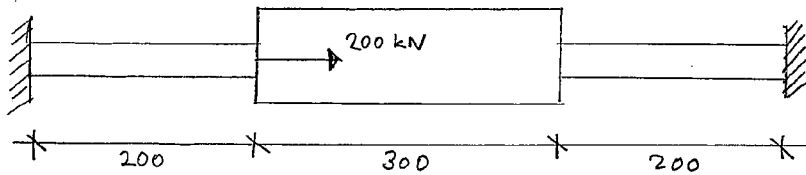
- for matrices up to 1000 unknowns it can be faster than partitioning.
- prescribed displacements substituted by very large numbers:

like very stiff Spring between node 1 and support

$$\begin{bmatrix} \rightarrow \beta & -k^{(2)} & 0 \\ -k^{(2)} & k^{(1)} + k^{(2)} & -k^{(1)} \\ 0 & -k^{(1)} & k^{(1)} \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix} = \begin{bmatrix} \beta \bar{w}_1 \\ -4 \\ 10 \end{bmatrix}$$

$\beta \sim$ average diagonal value in \underline{k} multiplied by $10^7 \Rightarrow$ the other terms in \underline{k}_{EF} become negligible and irrelevant

Example 2



$$k^{(1)} = \frac{E^{(1)} A^{(1)}}{L^{(1)}} = \frac{70 \cdot 10^9 \cdot 2400 \cdot 10^{-6}}{200} = 84 \cdot 10^4 \text{ Nm}^{-1}$$

$$k^{(3)} = k^{(1)}, \quad k^{(2)} = \frac{E^{(2)} A^{(2)}}{L^{(2)}} = 40 \cdot 10^4 \text{ Nm}^{-1}$$

$$A^{(1)} = A^{(3)} = 2400 \text{ mm}^2$$

$$E^{(1)} = E^{(3)} = 70 \text{ GPa}$$

$$A^{(2)} = 3000 \text{ mm}^2$$

$$E^{(2)} = 40 \text{ GPa}$$

$$\underline{k}^{(1)} = \underline{k}^{(3)} = 84 \cdot 10^4 \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$\underline{k}^{(2)} = 40 \cdot 10^4 \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

assembly of global matrices:

$$\underline{K} = \begin{matrix} & \textcircled{1} & \textcircled{2} & \textcircled{3} & \textcircled{4} \\ \begin{matrix} \textcircled{1} \\ \textcircled{2} \\ \textcircled{3} \\ \textcircled{4} \end{matrix} & \begin{bmatrix} 84 & -84 & 0 & 0 \\ -84 & 84+40 & -40 & 0 \\ 0 & -40 & 40+84 & -84 \\ 0 & 0 & -84 & 84 \end{bmatrix} & \cdot 10^4 & \begin{matrix} \rightarrow \underline{K}_E = \begin{bmatrix} 84 & 0 \\ 0 & 84 \end{bmatrix} \cdot 10^4 \\ \rightarrow \underline{K}_{EF}^T = \begin{bmatrix} -84 & 0 \\ 0 & -84 \end{bmatrix} \cdot 10^4 \\ \rightarrow \underline{K}_F = \begin{bmatrix} 124 & -40 \\ -40 & 124 \end{bmatrix} \cdot 10^4 \end{matrix} \\ \text{[N}_m^{-1}\text{]} \end{matrix}$$

$$\underline{f} = \begin{bmatrix} 0 \\ 200 \\ 0 \\ 0 \end{bmatrix} \cdot 10^3 \quad \left. \begin{matrix} \\ \\ \\ \end{matrix} \right\} \underline{f}_F \quad \text{[N]}$$

$$\underline{d} = \begin{bmatrix} 0 \\ w_2 \\ w_3 \\ 0 \end{bmatrix} \quad \left. \begin{matrix} \\ \\ \\ \end{matrix} \right\} \underline{d}_F \quad \text{[m]}$$

$$\underline{r} = \begin{bmatrix} r_1 \\ 0 \\ 0 \\ r_4 \end{bmatrix} \quad \text{[N]}$$

$$\underline{d}_F = \underline{K}_F^{-1} \left(\underline{f}_F - \underline{K}_{EF}^T \underline{d}_E \right) = \begin{bmatrix} 124 & -40 \\ -40 & 124 \end{bmatrix}^{-1} \cdot 10^{-4} \cdot \left(\begin{bmatrix} 200 \\ 0 \end{bmatrix} \cdot 10^3 - \begin{bmatrix} -84 & 0 \\ 0 & -84 \end{bmatrix} \cdot 10^4 \cdot \begin{bmatrix} 0 \\ 0 \end{bmatrix} \right) =$$

$$= \begin{bmatrix} 0,180023 \\ 0,058072 \end{bmatrix} \text{ m}$$

$$\underline{r}_E = \underline{K}_E \underline{d}_E + \underline{K}_{EF} \underline{d}_F = \begin{bmatrix} 84 & 0 \\ 0 & 84 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix} + \begin{bmatrix} -84 & 0 \\ 0 & -84 \end{bmatrix} \cdot 10^4 \begin{bmatrix} 0,180023 \\ 0,058072 \end{bmatrix} =$$

$$= \begin{bmatrix} -151,22 \\ -48,78 \end{bmatrix} \text{ kN}$$

[kN]

$$\sum X: -151,22 + 200 - 48,78 = 0 \quad \checkmark$$

strains: $\epsilon^{(i)} = \frac{w_2^{(i)} - w_1^{(i)}}{L^{(i)}}$, stresses: $\sigma^{(i)} = E^{(i)} \epsilon^{(i)}$

$$\sigma^{(1)} = \frac{w_2^{(1)} - w_1^{(1)}}{L^{(1)}} E^{(1)} = \frac{0,180023}{200} \cdot 70 \cdot 10^9 = 63 \text{ MPa (tension)}$$

$$\sigma^{(2)} = \frac{w_2^{(2)} - w_1^{(2)}}{L^{(2)}} E^{(2)} = \frac{0,058072 - 0,180023}{300} \cdot 40 \cdot 10^9 = -16,3 \text{ MPa (compression)}$$

$\sigma^{(3)}$... accordingly