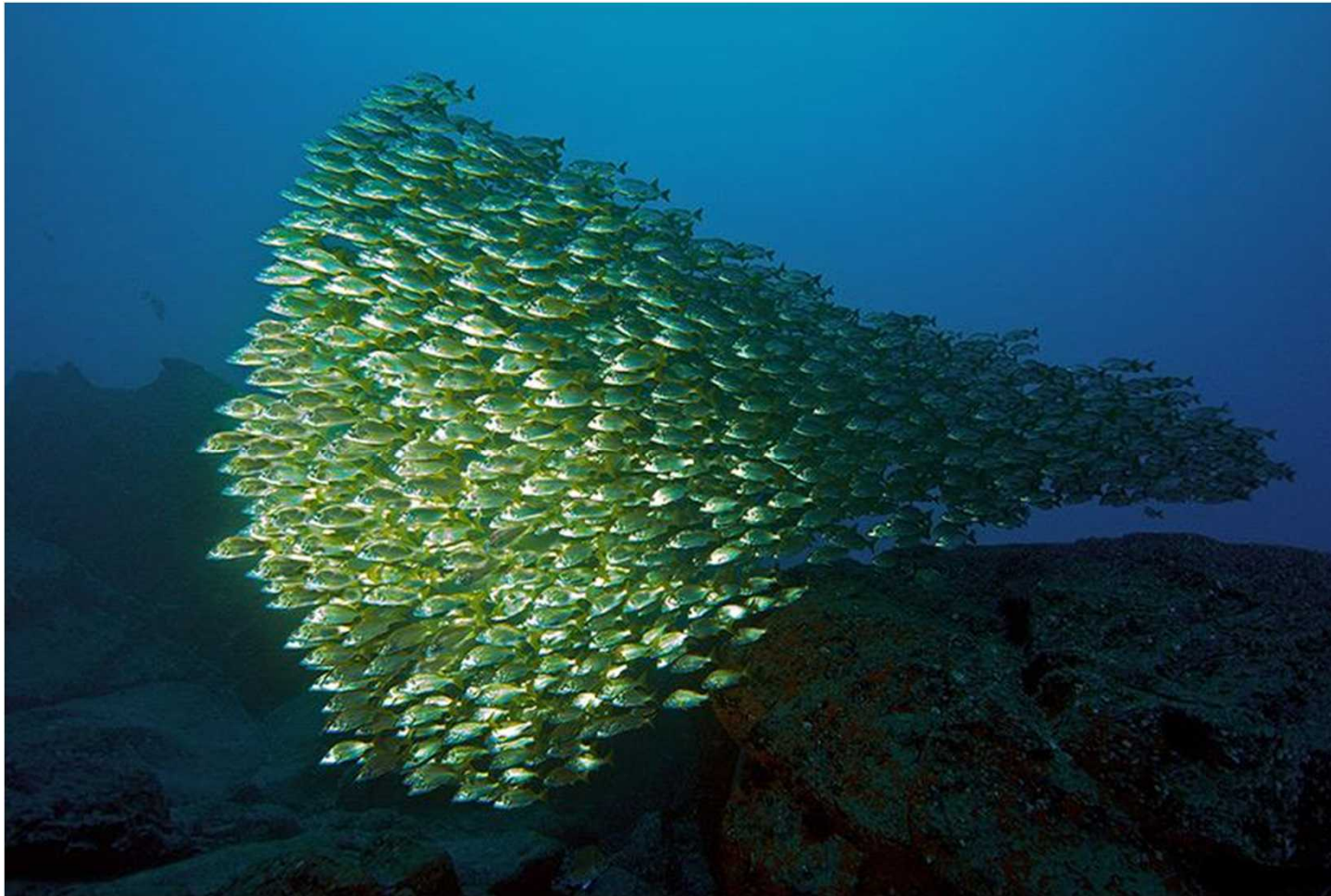


# Swarm Intelligence



<http://pixdaus.com/single.php?id=168307>

# Swarm Intelligence

- algorithms inspired by bird flocking, fish schooling, insect colonies etc.
- Particle Swarm Optimization
- Ant Colony Optimization
- Glow-worm Swarm Optimization
- ...
- different behaviour in transfer of information

# Swarm Intelligence

## Advantages:

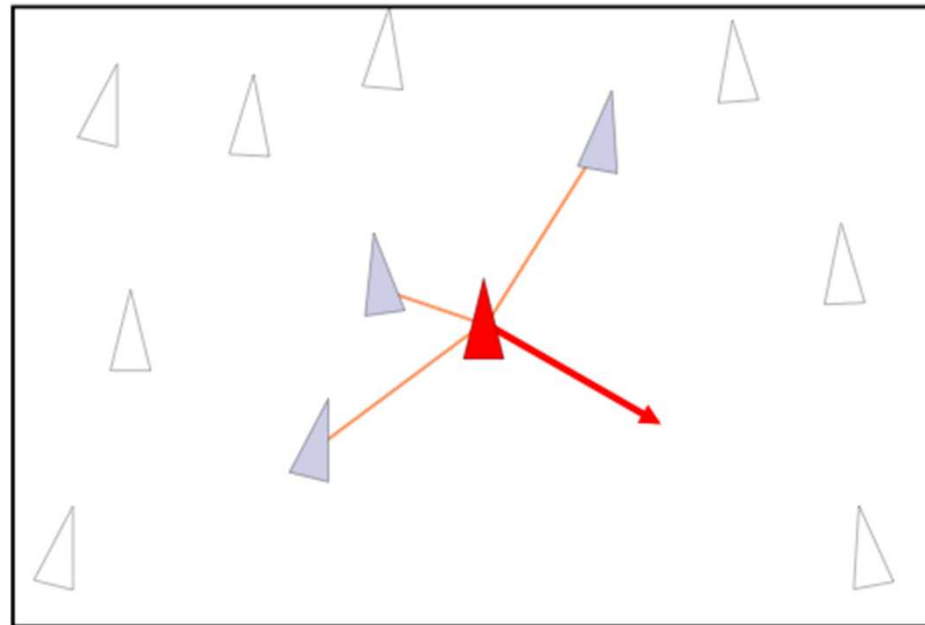
- easy to implement
- it is not necessary to calculate gradients or Hessian matrix

## Disadvantages:

- it is necessary to determine correctly all constants and parameters for a given task

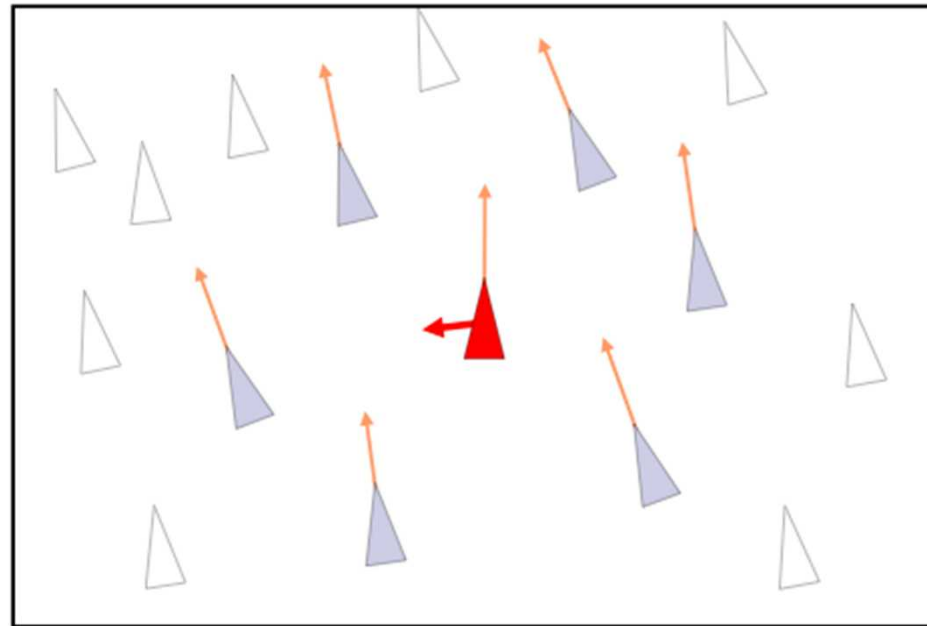
# Rules of Swarm Intelligence

Rule no. 1: Avoid Collision with neighboring birds



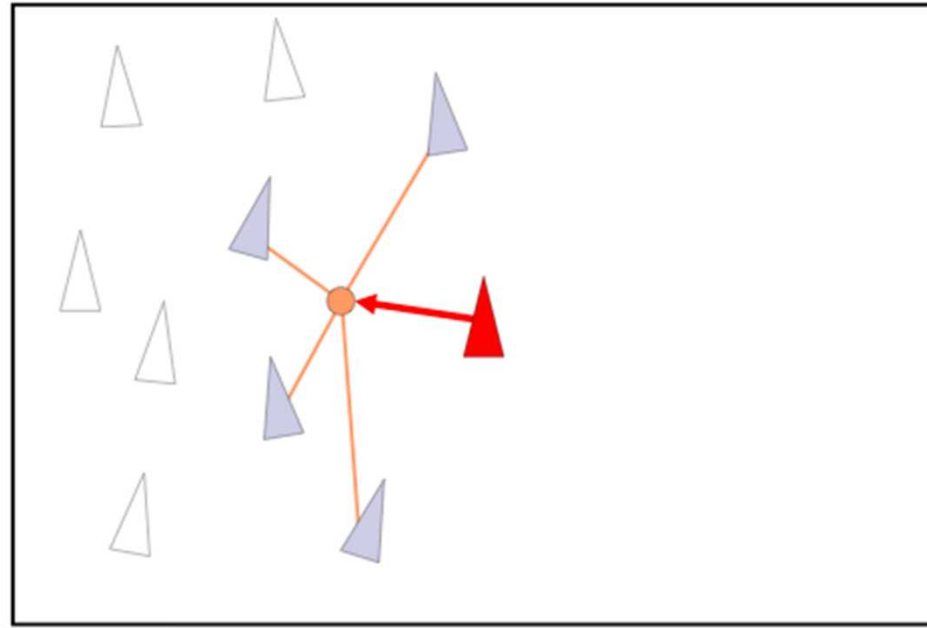
# Rules of Swarm Intelligence

Rule no. 2: Match the velocity of neighboring birds



# Rules of Swarm Intelligence

Rule no. 3: Stay near neighboring birds



# Particle Swarm Optimization



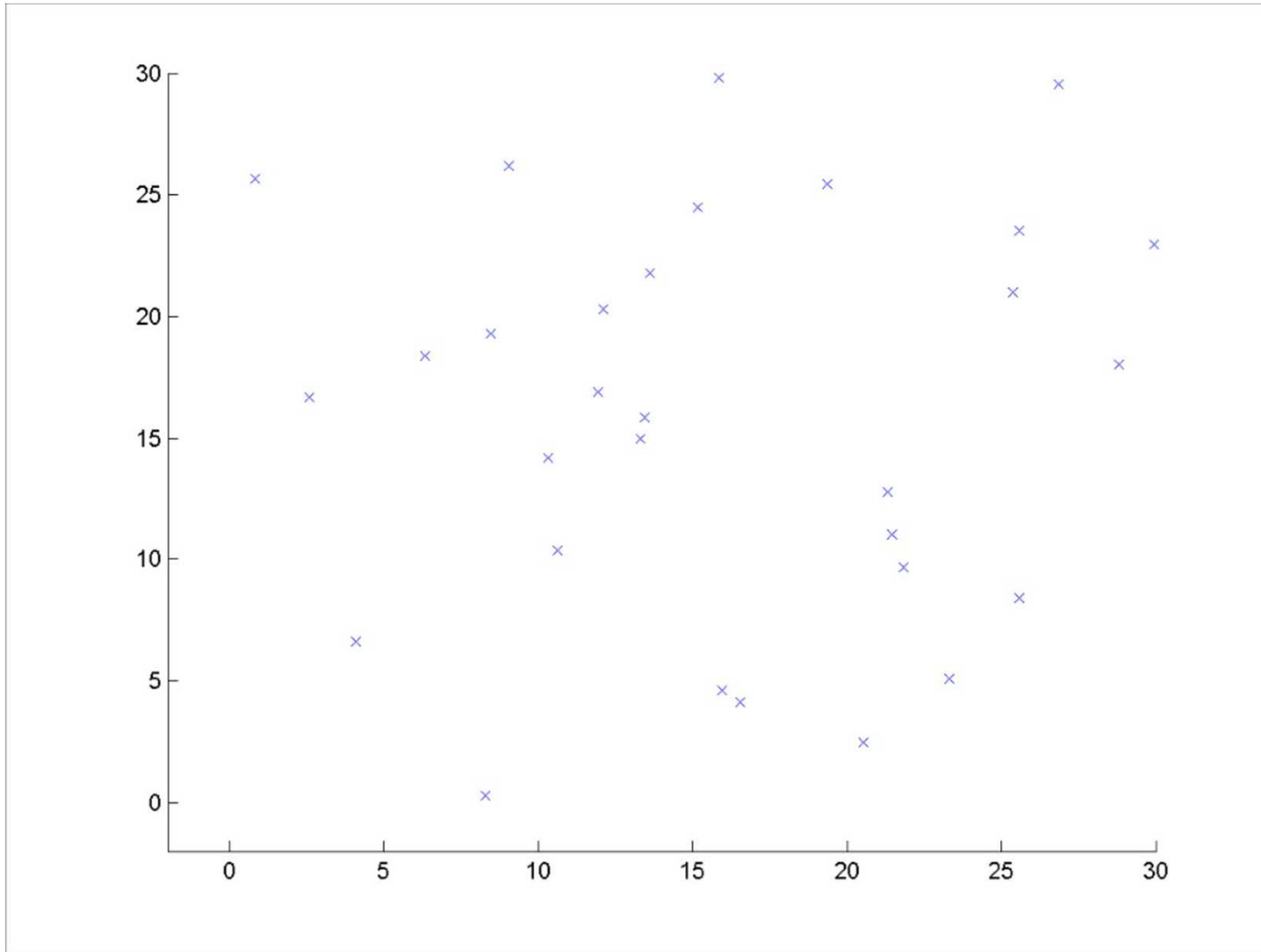
<http://www.crackedcamera.com/flock-of-birds-san-diego-ca/>

# Particle Swarm Optimization

- firstly published in 1995 by authors Kennedy and Eberhart [1]
- stochastic method
- it is not necessary to calculate gradients or Hessian matrix
- for discrete, continuous and combined problems



# Particle Swarm Optimization



# Particle Swarm Optimization

Original approach:

$$v_{id}^{k+1} = w \cdot v_{id}^k + c_1 \cdot rand() \cdot (p_{id} - x_{id}) + c_2 \cdot Rand() \cdot (p_{gd} - x_{id})$$

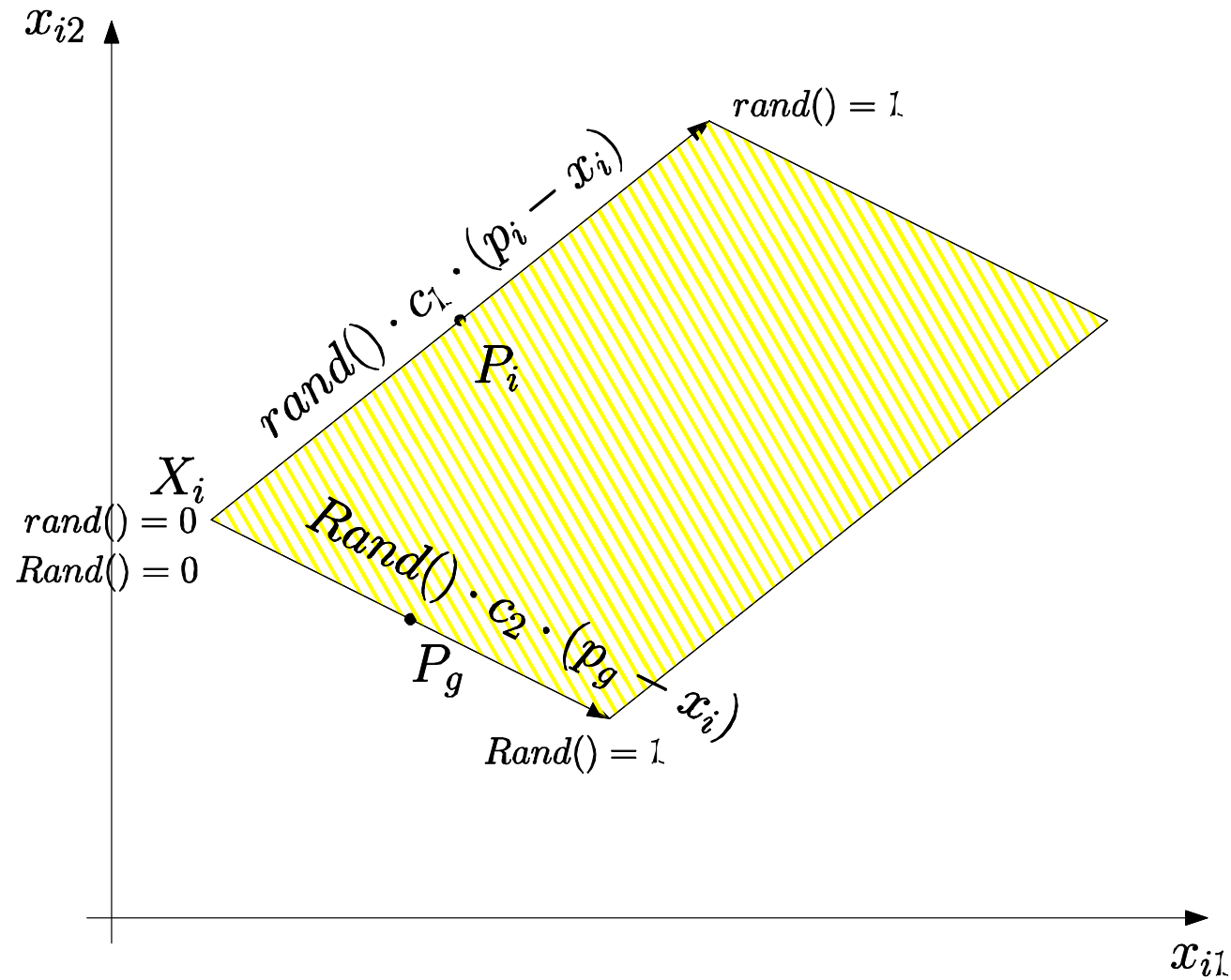
$$x_{id}^{k+1} = x_{id}^k + v_{id}^{k+1}$$

w – inertia weight

c<sub>1</sub> – cognitive factor

c<sub>2</sub> – social factor

# Stochastic contribution to velocity



# Particle Swarm Optimization

Constriction method (Clerc, 1999) [2, 3]

$$v_{id}^{k+1} = K \cdot \left[ v_{id}^k + c_1 \cdot rand() \cdot (p_{id} - x_{id}) + c_2 \cdot Rand() \cdot (p_{gd} - x_{id}) \right]$$

$$K = \frac{2}{\left| 2 - \varphi - \sqrt{\varphi^2 - 4\varphi} \right|}, \text{ where: } \varphi = c_1 + c_2, \varphi > 4$$

$$x_{id}^{k+1} = x_{id}^k + v_{id}^{k+1}$$

K – constriction factor

# Orientation values of parameters

$C_1, C_2$	2
rand(), Rand()	(0, 1)
w	0,4 - 0,9 for const.
K	0,729 (for $\phi = 4,1$ )

Notes: w - analogy to SA  
- it is possible to use constant values,  
linearly changing values etc.

# Algorithm

setting of constants, factors, ...

initial placement of particles in space

setting of initial velocity

while (termination condition != true )

    k++                           % cycle iteration

    for i = 1 : number of particles

        enumeration of an objective function  $f_i^k$

        if ( $f_i^k < p_i$ ) then  $p_i = f_i^k$

        if ( $f_i^k < p_g$ ) then  $p_g = f_i^k$

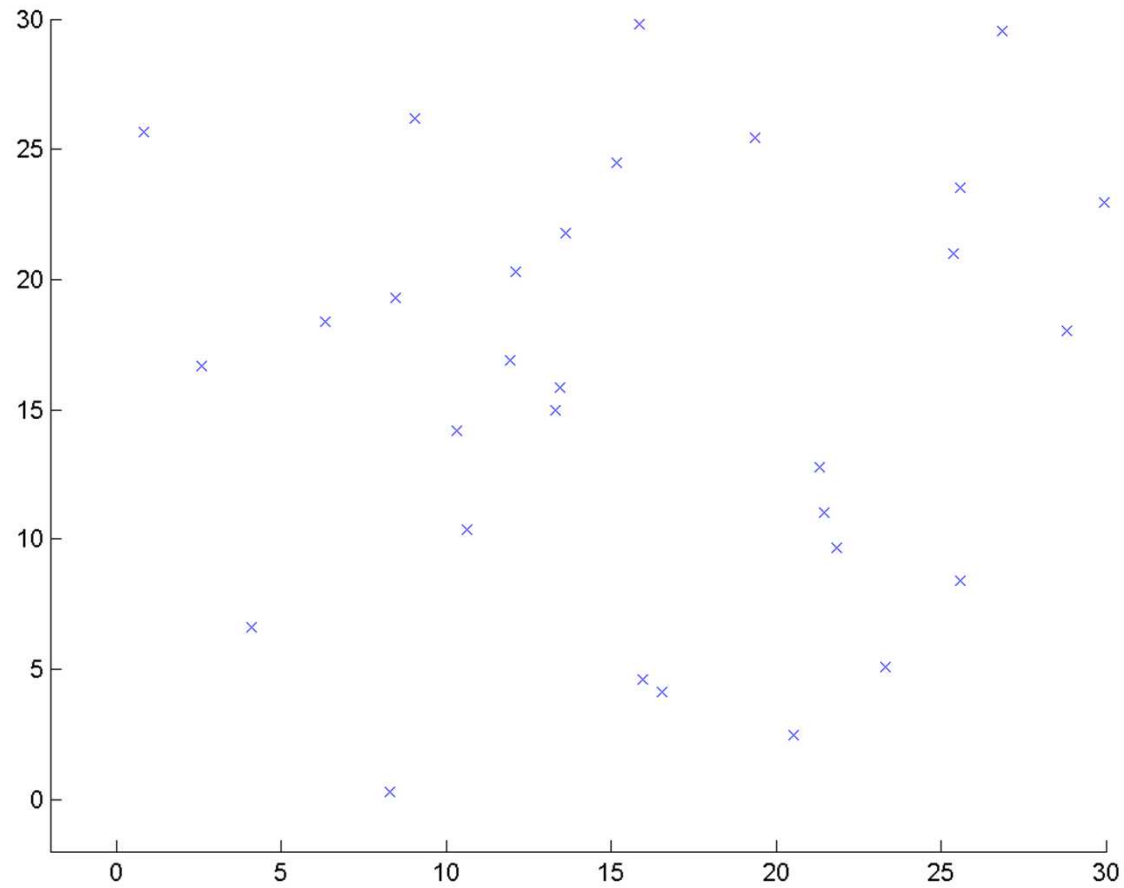
        updating particle velocity  $V_i$

        updating particle location  $X_i$

    end

end

# PSO.m



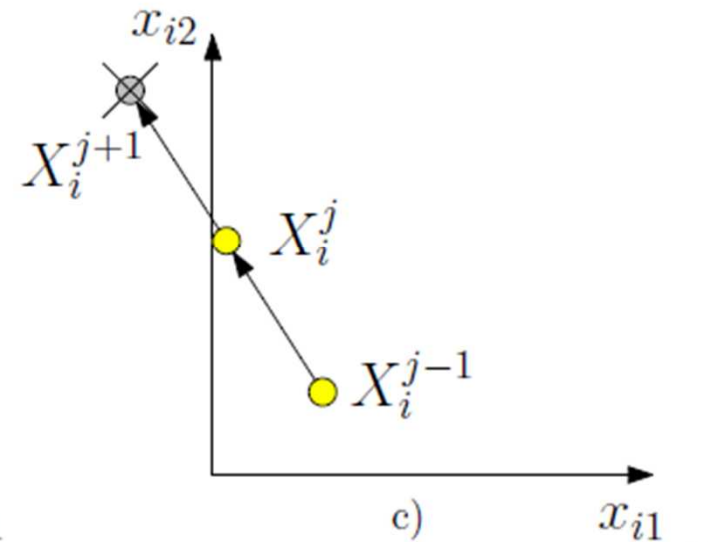
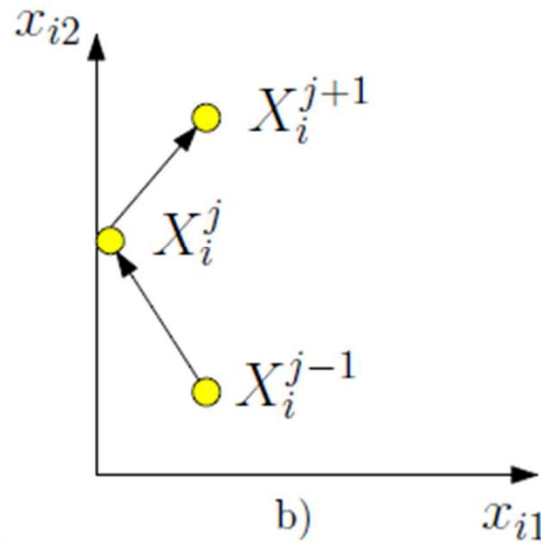
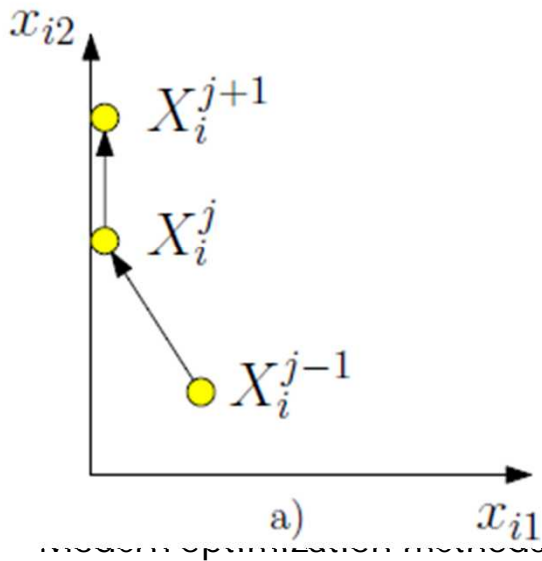
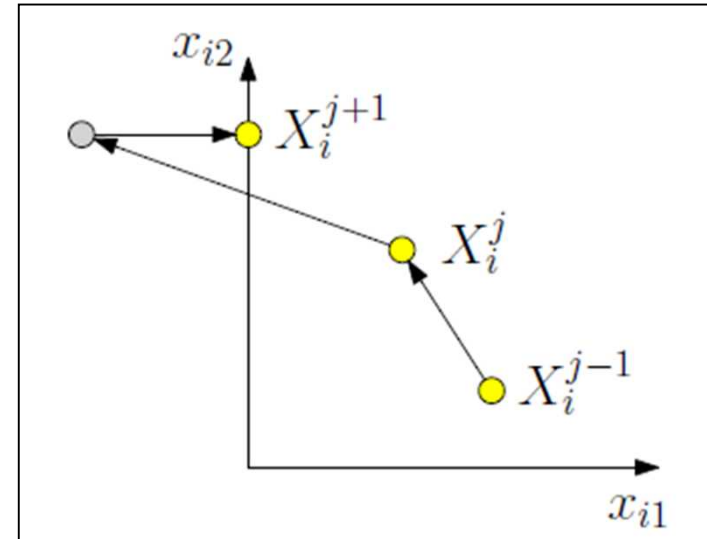
# PSO variants [4]

- random reinitialization of particle velocities
- maximum velocity restriction
  - restriction of vector length
  - restriction of each component of the vector
- minimum velocity restriction
- craziness
- inertia weight (constant value, linearly changing value, ...)
- constriction factor
- and many others

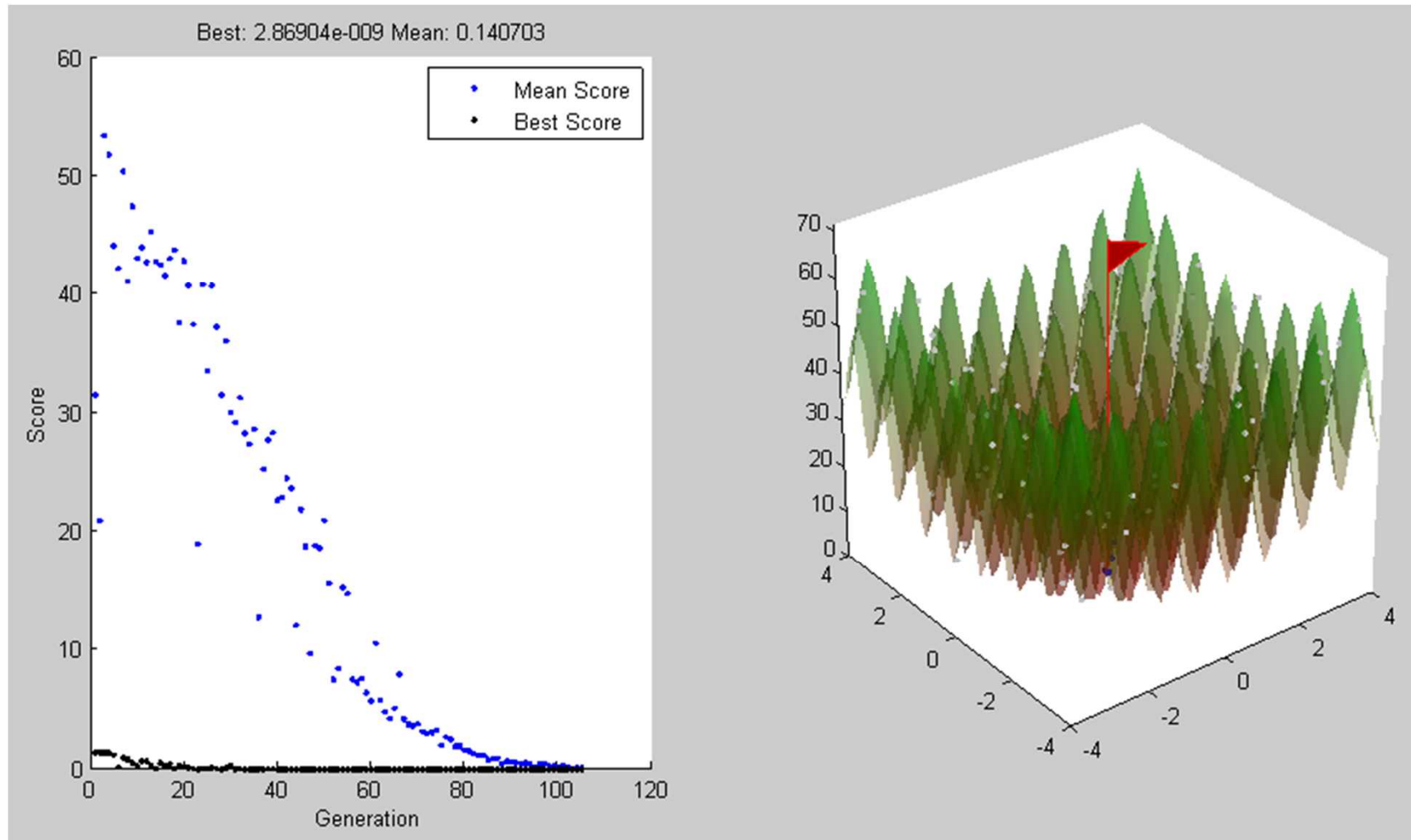


# Boundary conditions

- Absorbing wall
- Reflecting wall
- Invisible wall



# Another Particle Swarm Toolbox



# References

- [1] Kennedy, J.; Eberhart, R. C. (1995). Particle Swarm Optimization. IEEE International Conference of Neural Networks, 4: 1942 – 1948.
- [2] Clerc, M. (1999). The Swarm and The Queen: Towards a Deterministic and Adaptive Particle Swarm Optimization. IEEE Congress on Evolutionary Computation CEC'99, 3: 1951 – 1957.
- [3] Eberhart, R. C.; Shi, Y. (2000). Comparing Inertia Weights and Constriction Factors in Particle Swarm Optimization. IEEE Congress on Evolutionary Computation, 1: 84 – 88.
- [4] Wilke, D. N.; Kok, D.; Groenwold, A. A. (2006). Comparison of Linear and Classical Velocity Update Rules in Particle Swarm Optimization : Notes on Diversity. International Journal for Numerical Methods in Engineering, 70: 962 – 984.

# References

- [5] Shi, Y.; Eberhart, R. C. (1999). Empirical Study of Particle Swarm Optimization. IEEE Congress on Evolutionary Computation CEC'99, 3: 1945 – 1950.
- [6] Clerc, M. (2006). Particle Swarm Optimization. 1. ed. Wiley-ISTE. ISBN-13: 978-1-905209-04-0

# Ant Colony Optimization

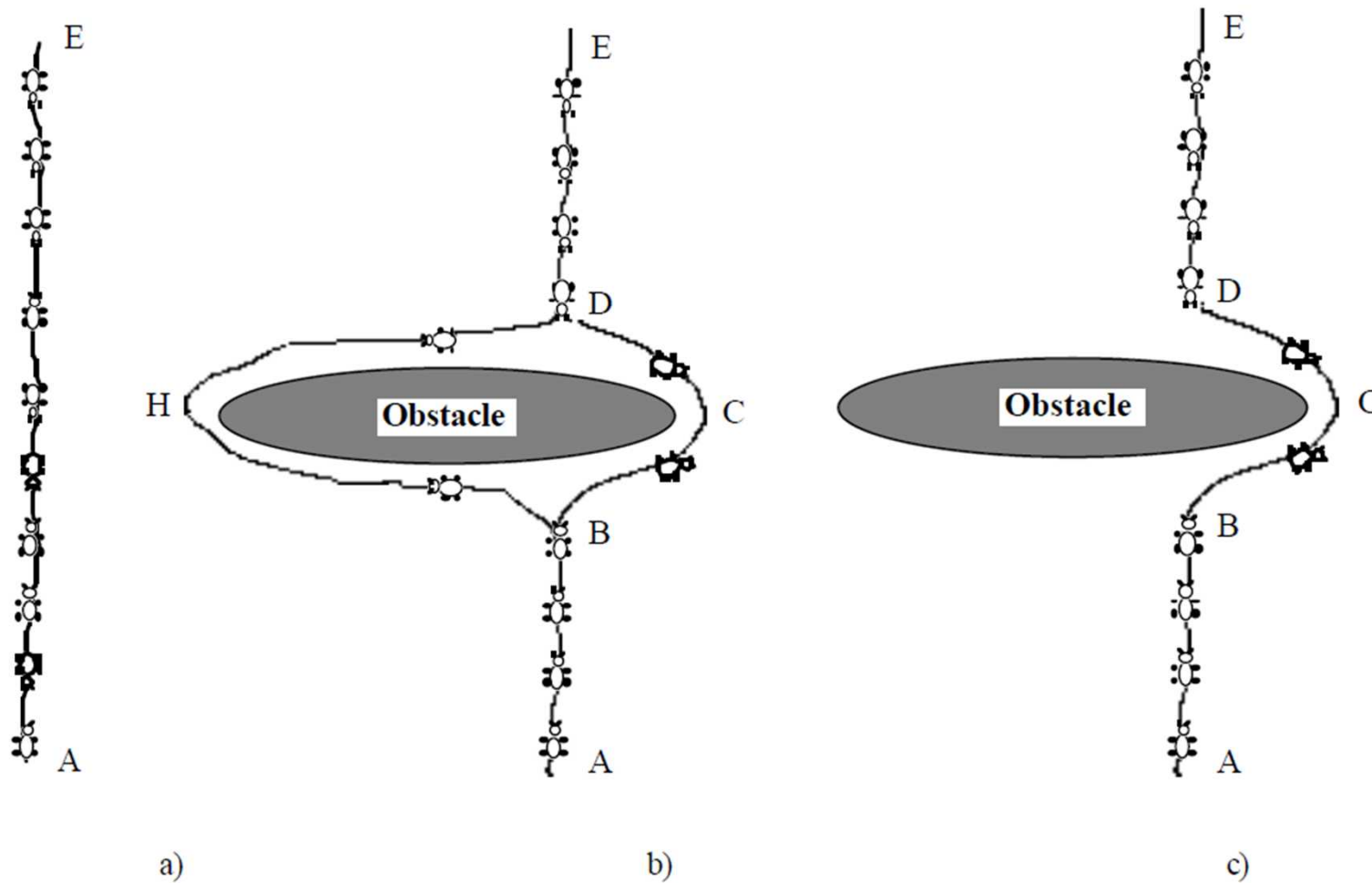


<http://ananthu-howtonameit.blogspot.com/2010/11/secret-of-success-get-mind-set-of-ant.html>

# Ant Colony Optimization

- first published in 90's by M. Dorigo et al.
- stochastic method
- it is not necessary to calculate gradients or Hessian matrix
- algorithm was originally tested on TSP (Travelling Salesman Problem)
  
- pheromone

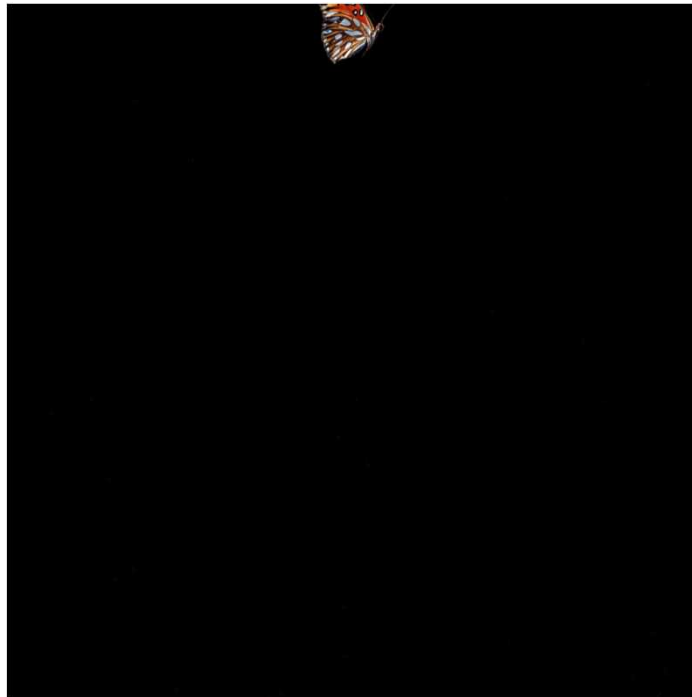
# Ant Colony Optimization



published in [7]

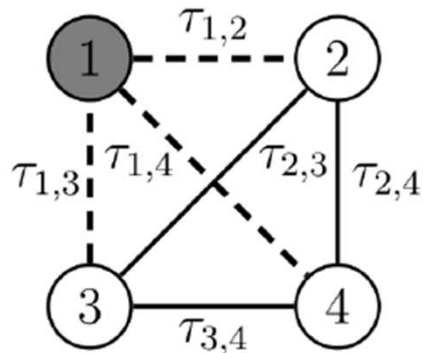
# Ant Colony Optimization

<http://users.sussex.ac.uk/~tn41/antStage2/war/AntAppletFull.html>



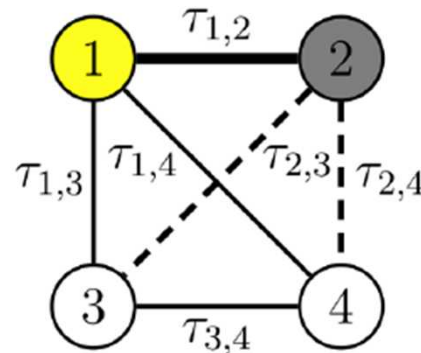


# Travelling Salesman Problem



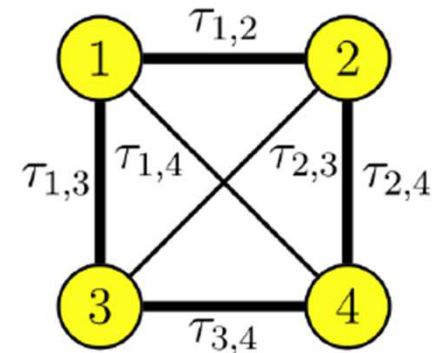
$$\mathbf{p}(e_{1,j}) = \frac{\tau_{1,j}}{\tau_{1,2} + \tau_{1,3} + \tau_{1,4}}$$

(a) First step of the solution construction.



$$\mathbf{p}(e_{2,j}) = \frac{\tau_{2,j}}{\tau_{2,3} + \tau_{2,4}}$$

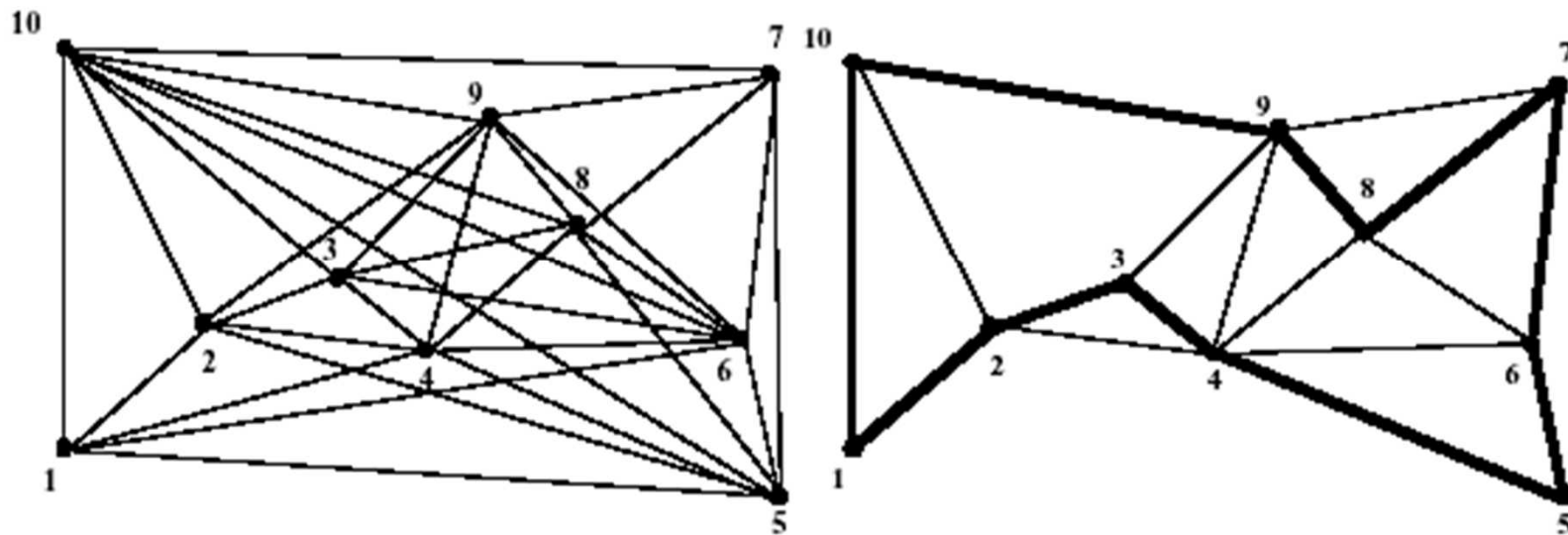
(b) Second step of the solution construction.



(c) The complete solution after the final construction step.

published in [8]

# Travelling Salesman Problem



# Algorithm

setting ant number and their random locations

setting initial pheromone values

while (termination condition != true )

    t++                                   % cycle iteration (time)

    constructing ant solutions

    (local search)

    updating pheromone values

    relocation of ants

end

# Ant Colony Optimization

- Ant System (AS)
- *MAX-MIN* Ant System
- Ant Colony System
- Hyper-cube AS

# Methods of pheromone updating

- Ant System
  - pheromone values are updated by all ants

$$\tau_{ij}^{t+1} = (1 - \rho) \cdot \tau_{ij}^t + \sum_{k=1}^m \Delta \tau_{ij}^t, \quad \Delta \tau_{ij}^t = \begin{cases} Q / L_k^* \\ 0^{**} \end{cases}$$

\* if  $k$ -ant used edge  $(i,j)$  on its tour

\*\* otherwise

# Methods of pheromone updating

- *MAX-MIN* Ant System
  - pheromone values are updated by individual ants with the best solution found (best in each iteration, best of all)

$$\tau_{ij}^{t+1} = \left[ (1 - \rho) \cdot \tau_{ij}^t + \Delta \tau_{ij}^{best} \right]_{\tau_{\min}}^{\tau_{\max}},$$

$$\Delta \tau_{ij}^{best} = \begin{cases} 1 / L_{best}^* \\ 0^{**} \end{cases}$$

\* if  $(i,j)$  belongs to the best tour

\*\* otherwise

# Methods of pheromone updating

- Ant Colony System

- local pheromone update after each iteration by all ants

$$\tau_{ij} = (1 - \varphi) \cdot \tau_{ij} + \varphi \cdot \tau_0$$

- global pheromone update at the end of iteration as in *MAX-MIN AS*

$$\tau_{ij} = \begin{cases} (1 - \rho) \cdot \tau_{ij} + \rho \cdot \Delta\tau_{ij}^* \\ \tau_{ij}^{**} \end{cases}$$

\* if  $(i,j)$  belongs to the best tour,  $\Delta\tau_{ij} = 1/L_{best}$

\*\* otherwise

# References

- [7] Colorni, A.; Dorigo, M.; Maniezzo, V. (1991). Distributed Optimization by Ant Colonies. In European Conference on Artificial Life, 134-142.
- [8] Blum, Ch. (2005). Ant Colony Optimization: Introduction and Recent Trends. Physics of Life Reviews, 2(4): 353 – 373.
- [9] Dorigo, M. (2004). Ant Colony Optimization. 1. vyd. The MIT Press. ISBN: 978-0262042192.
- [10] Dorigo, M.; Birattari, M.; Stutzle, T. (2006). Ant Colony Optimization: Artificial Ants as a Computational Intelligence Technique. Technical Report No. RT/IRIDIA/2006-023, Université Libre de Bruxelles, IRIDIA.



# Swarm Intelligence - summary

- stochastic methods – do not guarantee the global optima retrieval
- difference in „communication“
  - PSO – on swarm level
  - ACO – locally by pheromones

# References

<http://www.mathworks.com/matlabcentral/fileexchange/11559-particle-swarm-optimization-simulation>

<http://www.mathworks.com/matlabcentral/fileexchange/25986-another-particle-swarm-toolbox>

<http://www.liacs.nl/~baeck/NC/slides/Applet/ants.html>

<http://www.mathworks.com/matlabcentral/fileexchange/14543>

**A humble plea.** Please feel free to e-mail any suggestions, errors and typos to **matej.leps@fsv.cvut.cz**.

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*Version: 001*